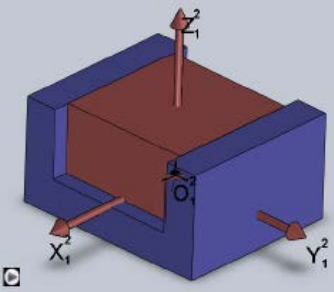

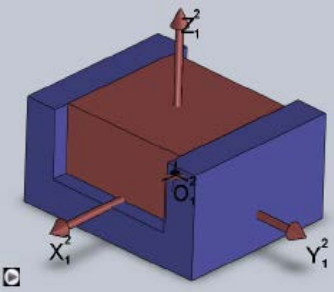
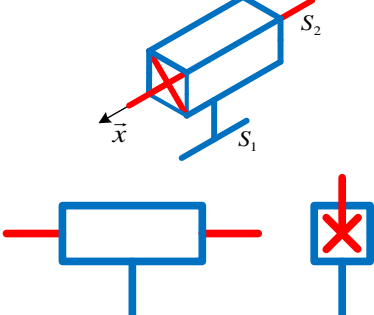
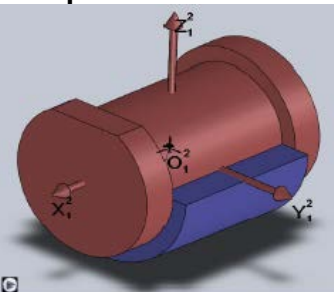
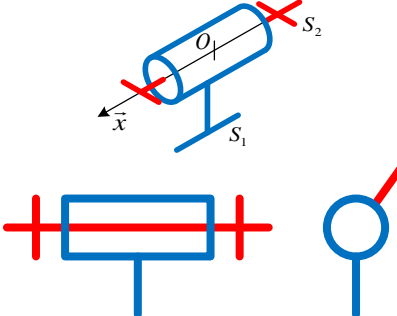
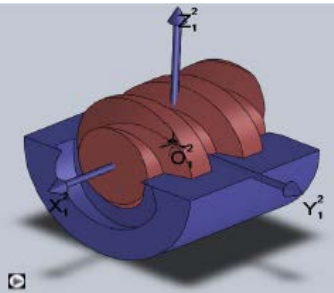
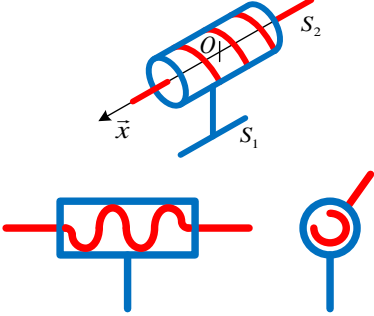
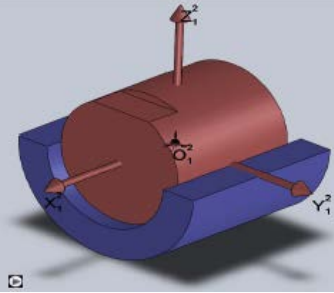
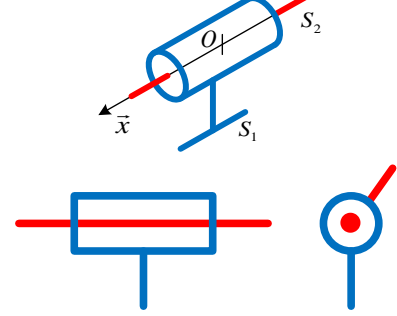
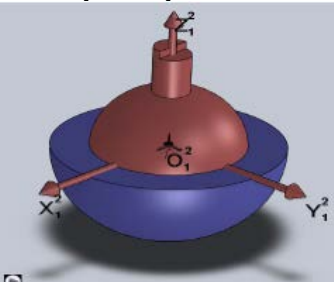
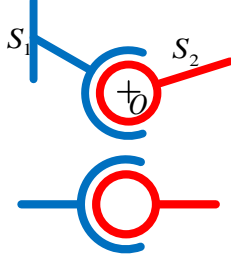
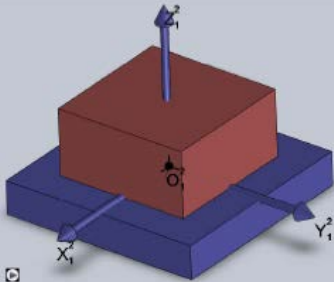
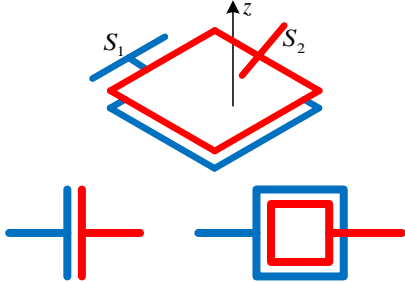
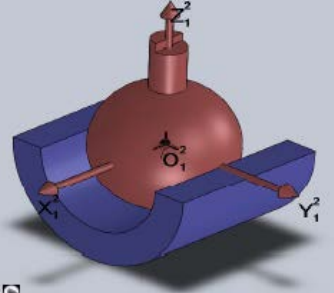
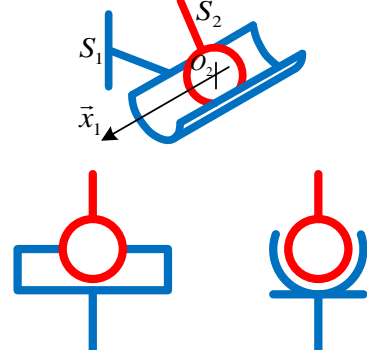
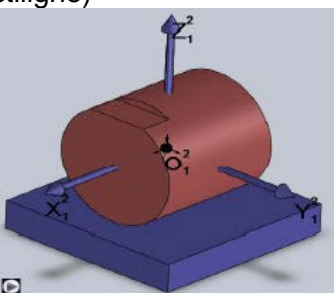
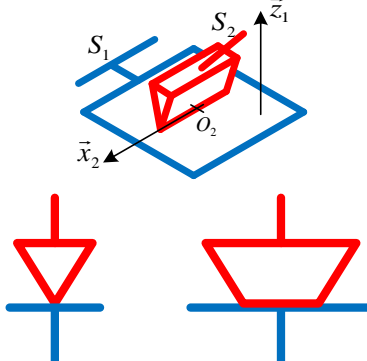
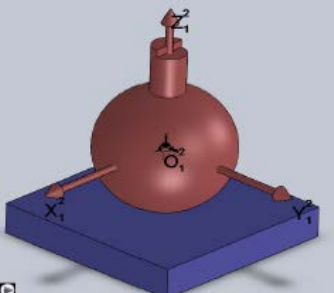
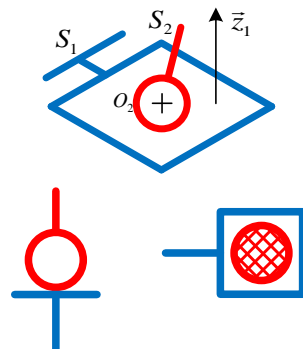


Liaison	Schématisation	Propriétés												
Liaison encastrement 		Degré de liberté : n=0 <table border="1"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>0</td> <td>0</td> </tr> <tr> <td>Y</td> <td>0</td> <td>0</td> </tr> <tr> <td>Z</td> <td>0</td> <td>0</td> </tr> </tbody> </table>		T	R	X	0	0	Y	0	0	Z	0	0
	T	R												
X	0	0												
Y	0	0												
Z	0	0												
Liaison glissière 		Degré de liberté : n=1 Tableau des mobilités : <table border="1"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>1</td> <td>0</td> </tr> <tr> <td>Y</td> <td>0</td> <td>0</td> </tr> <tr> <td>Z</td> <td>0</td> <td>0</td> </tr> </tbody> </table> Contact : sur un cylindre de base non circulaire.		T	R	X	1	0	Y	0	0	Z	0	0
	T	R												
X	1	0												
Y	0	0												
Z	0	0												
Liaison pivot 		Degré de liberté : n=1 Tableau des mobilités : <table border="1"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>0</td> <td>1</td> </tr> <tr> <td>Y</td> <td>0</td> <td>0</td> </tr> <tr> <td>Z</td> <td>0</td> <td>0</td> </tr> </tbody> </table> Contact : sur une surface de révolution.		T	R	X	0	1	Y	0	0	Z	0	0
	T	R												
X	0	1												
Y	0	0												
Z	0	0												
Liaison hélicoïdale 		Degré de liberté : n=1 Tableau des mobilités : <table border="1"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>1</td> <td>1</td> </tr> <tr> <td>Y</td> <td>0</td> <td>0</td> </tr> <tr> <td>Z</td> <td>0</td> <td>0</td> </tr> </tbody> </table>		T	R	X	1	1	Y	0	0	Z	0	0
	T	R												
X	1	1												
Y	0	0												
Z	0	0												
Liaison pivot glissant 		Degré de liberté : n=2 Tableau des mobilités : <table border="1"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>1</td> <td>1</td> </tr> <tr> <td>Y</td> <td>0</td> <td>0</td> </tr> <tr> <td>Z</td> <td>0</td> <td>0</td> </tr> </tbody> </table> Contact : sur un cylindre de base circulaire.		T	R	X	1	1	Y	0	0	Z	0	0
	T	R												
X	1	1												
Y	0	0												
Z	0	0												

<p>Liaison sphérique</p> 		<p>Degré de liberté : $n=3$ Tableau des mobilités :</p> <table border="1" data-bbox="1069 280 1300 425"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>0</td> <td>1</td> </tr> <tr> <td>Y</td> <td>0</td> <td>1</td> </tr> <tr> <td>Z</td> <td>0</td> <td>1</td> </tr> </tbody> </table> <p>Contact : sur une sphère.</p>		T	R	X	0	1	Y	0	1	Z	0	1
	T	R												
X	0	1												
Y	0	1												
Z	0	1												
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	T	R												
X	1	0												
Y	1	0												
Z	0	1												
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	T	R												
X	1	1												
Y	0	1												
Z	0	1												
<p>Liaison cylindre-plan (rectiligne)</p> 		<p>Degré de liberté : $n=4$ Tableau des mobilités :</p> <table border="1" data-bbox="1069 1321 1300 1467"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>1</td> <td>1</td> </tr> <tr> <td>Y</td> <td>1</td> <td>0</td> </tr> <tr> <td>Z</td> <td>0</td> <td>1</td> </tr> </tbody> </table> <p>Contact : un cylindre sur un plan (axe du cylindre astreint à rester sur un plan décalé du plan réel de contact d'un rayon du cylindre).</p>		T	R	X	1	1	Y	1	0	Z	0	1
	T	R												
X	1	1												
Y	1	0												
Z	0	1												
<p>Liaison sphère-plan</p> 		<p>Degré de liberté : $n=5$ Tableau des mobilités :</p> <table border="1" data-bbox="1069 1713 1300 1859"> <thead> <tr> <th></th> <th>T</th> <th>R</th> </tr> </thead> <tbody> <tr> <td>X</td> <td>1</td> <td>1</td> </tr> <tr> <td>Y</td> <td>1</td> <td>1</td> </tr> <tr> <td>Z</td> <td>0</td> <td>1</td> </tr> </tbody> </table> <p>Contact : une sphère sur un plan (centre de la sphère astreint à rester sur un plan décalé du plan réel de contact d'un rayon de la sphère).</p>		T	R	X	1	1	Y	1	1	Z	0	1
	T	R												
X	1	1												
Y	1	1												
Z	0	1												